

ADVANCED FLEXIBLE MOUNTER CM-S21

Overview

CM-S21 Adopt servo motor driven system with 1 gantry and 6 spindle , and the motion centering technique of Gigabit six flying camera, the efficiency of mounting is greatly improved, and the bus control technology with the modular cabling makes machine running fast and stably.

- Theorical max mounting speed :18000 CPH
- Real mounting speed: around 10000 CPH
- 1 gantry* 6 Spindles
- Applicable parts :0402[~]28^{*}22mm
- SOP.QFP (H15mm)
- Applicable PCB :Min. 50(W)* 50(L)mm
- Max .300(W)*500(L)mm
- High speed ,high precision and electrically driven feeder
- Feeder station: 8mm Feeder *32pcs
- Rated power:1.5K

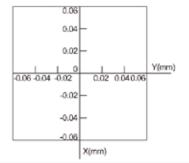
ADVANCED HIGH SPEED FLEXIBLE MOUNTER CM-S21

Realizes Placement Speed of 10,000 CPH (real mounting speed)

Realizes the highest placement speed of 10000 CPH with 6 spindles as well as optimized pickup/placement motion.

Placement Accuracy Correction System

Chip ±50µm(Cpk ≥1.0) The newly upgraded placement accuracy calibration system automatically checks and corrects the pickup point offset, head offset, C/V offset, etc. to allow reliable part placeme







Reinforced Applicability to Parts and PCBs

- Applicable to parts from 0402 to 28*22mm(H15mm) parts
- Applicable to Max. 500(L) x

Electrically Driven Speed and High Precision Feeder



Easy-operated Software

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	r Definition				17155							1
No.	Part	Description	Туре	Push	X	Y	Z	R	PartR	-	Dump	Ma
1				1	0.0000	0.0000	0.0000	0.0000	0		1	Normal
2				1	16.0000	0.0000	0.0000	0.0000	0		1	Normal
3				1	32.0000	0.0000	0.0000	0.0000	0		1	Normal
4				1	48.0000	0.0000	0.0000	0.0000	0		1	Normal
5				1	64.0000	0.0000	0.0000	0.0000	0		1	Normal
6				1	80.0000	0.0000	0.0000	0.0000	0		1	Normal
7				1	96.0000	0.0000	0.0000	0.0000	0	1	1	Normal
8				1	112.0000	0.0000	0.0000	0.0000	0		1	Normal
9			_	1	128.0000	0.0000	0.0000	0.0000	0		1	Normal
10				1	144.0000	0.0000	0.0000	0.0000	0		1	Normal
11			_	1	160.0000	0.0000	0.0000	0.0000	0		1	Normal
12				1	176.0000	0.0000	0.0000	0.0000	0		1	Normal
13				1	192.0000	0.0000	0.0000	0.0000	0		1	Normal
Teac	Teach ✓ Camera ▼ ✓ Move # Get		Unit Front		Clear	All Taps		Change Slot			Feeders al numb	
+			Open/Close		Offset		Feeder arrangement		ment	Monolithic translation		



	PCB Edk			Diegnosis	Sys.Setup		DLE	
	C:\Users\welcomtex	hiDesktopiTest/	QFP100-A_xml			H805-3.0	.0.2	
1/2	Production Info							
Start W				Start Time	00:00:00	F	Production	Plan
I► db.				Elapsed Time	00:00:00:	00		
ont. Fisish				Remaining Time	00:00:00	0	Reset	
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•	Placement Status Front Vie		_	8.65	-	_	-	
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-	Front Vie		Current Step Current Cycle		PCB Stop		al operation	PCB
	Front Vie	17		0 9			al operation	PCB
-	Front Vie	17 11 1	Current Cycle	0 °°	PCB Stop		a) operation	PCB

Specifications

Machine model	CM-S21
Alignment	Fiducial camera +mobile vision and stage vi
Number of Spindles	1 gantry *6 spindles
Driving method	X /Y/with servo motor, Z with step mo
Mounting speed	18000 CPH (max theorical mounting speed) 10000 CPH (real mounting speed)
Component range	0402~28*22mm SOP.QFP (H15
PCB	Min.50(w)*50(L)mm Standard:300(W)*500(L)mm Thickness: 0.5-4m
Conveyor	Only Left to right, 900+/-20mm
Feeder station	32 pcs *8m
Placement accuracy	$\pm 50 \mu m@\mu + 3\sigma$ (based on standard chips)
Power supply/air pressure	AC 220V /50HZ, 0.5~0.77Mpa
Power	1.5KW
Machine size	1310(L)*1280(W)*1420(H)mm